

Matched Source Waveform Inversion: Volume Extension

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TOTAL

Outline

- 1 Overview of Source-based WI
- 2 MSWI: Volume Extension
- 3 Analysis of Transmission Problem
- 4 Numerical Examples

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Overview of Source-based WI

Src-recv extension: $\bar{f} = \bar{f}(\mathbf{x}_r, \mathbf{x}_s, t) \in \mathbb{R}^3$ (or \mathbb{R}^5)

- Works for single arrival (traveltime tomography).
- Fail if multi-arrivals exist.
 - (1). Ambiguity when fitting data from different branches;
 - (2). Slope of traveltimes is lost (single trace fit).
 - (3). $G(\mathbf{x}_r, \mathbf{x}_s, t) * f_{sr}(t) = d(\mathbf{x}_r, \mathbf{x}_s, t)$ is NOT solvable in L_2 sense.

Space-time extension: $\bar{f} = \bar{f}(\mathbf{x}, \mathbf{x}_s, t) \in \mathbb{R}^4$ (or \mathbb{R}^6)

- Solve the problem (1)-(2), but no guarantee for (3).
- Limitation to 3D Helmholtz eqn solver.
- Huge storage requirement of $\bar{f}(\mathbf{x}, \mathbf{x}_s, t) \in \mathbb{R}^6$ in 3D.

Any other choices of source extn that can solve all the problems (1)-(3) and w/o limitation like space-time extn?

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Extended Modeling & Annihilator

Extended Modeling:

$\bar{f}(\mathbf{x}; \mathbf{x}_s)$: extended model of $\delta(\mathbf{x} - \mathbf{x}_s)$

Extended modeling operator $\bar{S}\bar{f} = \bar{u}$:

$$\frac{1}{v^2} \frac{\partial^2 \bar{u}}{\partial t^2} - \Delta \bar{u} = \bar{f}(\mathbf{x}, \mathbf{x}_s) \delta(t).$$

Presume that the recorded data is deconvolved by wavelet $f(t)$.

Annihilator:

$A = |\mathbf{x} - \mathbf{x}_s|$: Penalize non-focusing energy around src position \mathbf{x}_s .

Matched Source Waveform Inversion

Extended waveform inversion:

$$J_\alpha[v] = \frac{1}{2\alpha} \sum_{\mathbf{x}_r, \mathbf{x}_s} \int |\bar{S}[v]\bar{f} - d|^2 dt + \frac{1}{2} \sum_{\mathbf{x}_s} \int |A\bar{f}|^2 d\mathbf{x}$$

s.t. $(\bar{S}^T \bar{S} + \alpha A^T A)\bar{f} = \bar{S}^T d.$

Key feature: data fitting via $\bar{f} \Rightarrow$ no cycle skipping problem!

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Property of \bar{S} and $\bar{S}^T \bar{S}$

Lemma (FIO)

Under some mild assumption of velocity and there is no grazing rays, the extended source forward modeling operator \bar{S} is fourier integral operator.

Lemma (Ψ DO)

The extended normal operator $\bar{S}^T \bar{S}$ is Ψ DO of order -2 ,

$$\bar{S}^T \bar{S} \in \text{OPS}^{-2}$$

Furthermore, we have

$$\bar{S}^T \bar{S} \bar{f} = \frac{1}{(2\pi)^2} \int \frac{1}{|\mathbf{k}|^2} \frac{e^{i\mathbf{k} \cdot (\mathbf{y} - \mathbf{x})}}{4 \frac{\cos \alpha_r}{v_r}} \bar{f}(\mathbf{y}) d\mathbf{k} d\mathbf{y}$$

Ψ DO Verification of $\bar{S}^T \bar{S}$

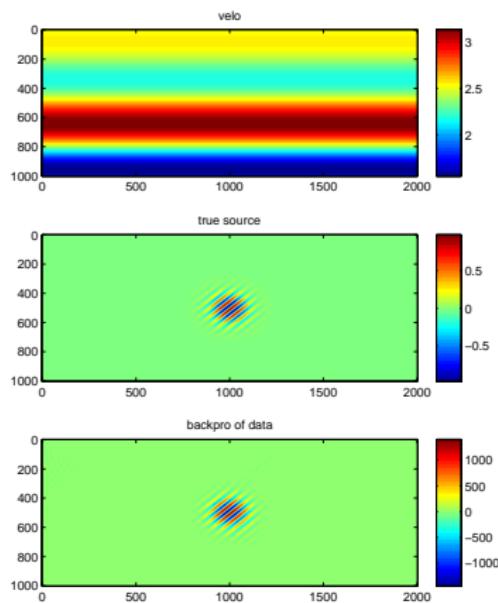


Figure: True velo, true source \bar{f} , and backpropagation field $\bar{S}^T \bar{S} \bar{f}$

Like the pair of **migration** and **demigration** operator!

Smooth Objective Functional

The direct consequence of these two lemmas yields the following important conclusion,

Theorem

The volume based MSWI objective functional $J_\alpha[v]$ is smooth function in velocity v independent of data spectrum.

Note that the objective function admits the bilinear form,

$$J_\alpha[v] = \frac{1}{2\alpha} \langle (I - \bar{S}N_\alpha^{-1}\bar{S}^T)d, d \rangle$$

See C. Stolk and W. Symes (IP-2000) for general argument.

Relation with Stereotomography

Theorem

The Hessian of MSWI function at the consistent data is equivalent to stereotomography,

$$\delta^2 J_\alpha[v^*] \approx C \left\| \frac{\partial}{\partial \theta_s} \delta\tau(\mathbf{x}_r, \mathbf{x}_s) \right\|^2 + O(\alpha).$$

where C is frequency independent constant.

NOTE:

$\delta\tau(\mathbf{x}_r, \mathbf{x}_s) = 0$ and $\frac{\partial}{\partial \mathbf{x}_r} \delta\tau(\mathbf{x}_r, \mathbf{x}_s) = 0$ is satisfied automatically by backpropagation.

See H. Chauris etc. (2002) for similar discussions.

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 - SEAM Phase I Model
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Model

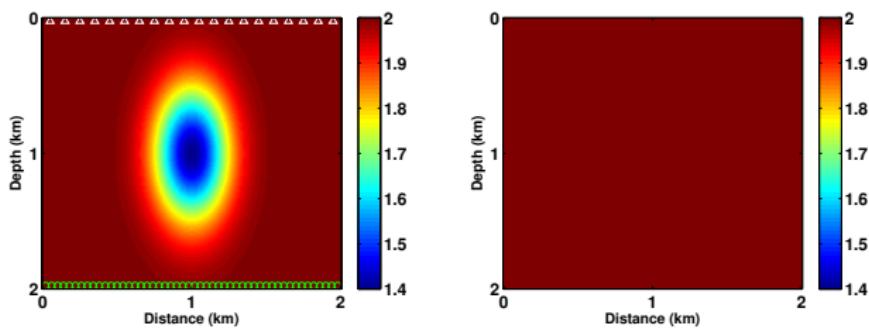


Figure: Transmission configuration: true model and initial model

Data

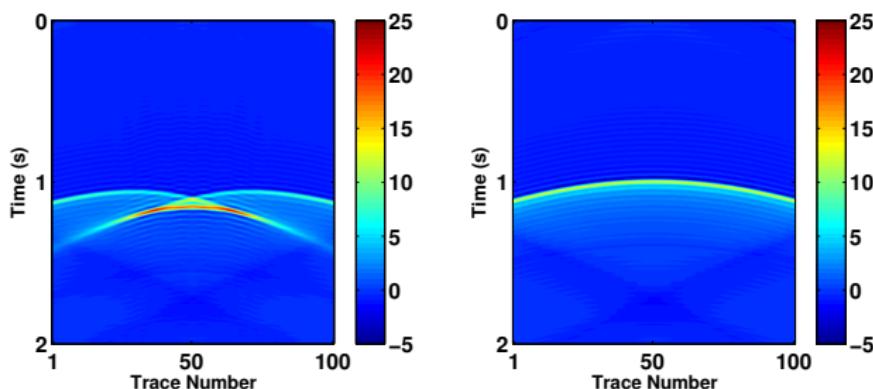


Figure: Recorded data and simulated data with initial model at center shot $x_s = 1$ km

Inverted Velocity

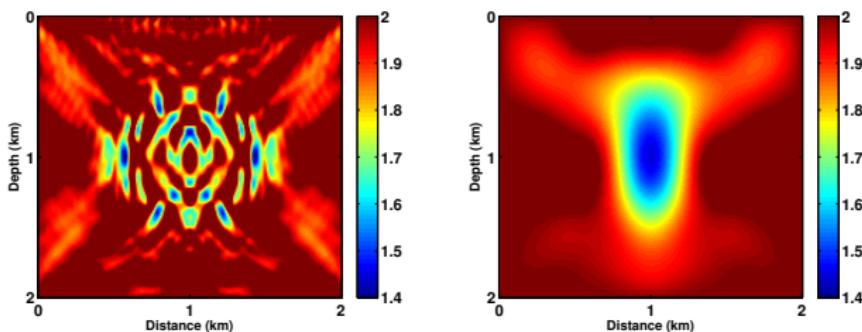


Figure: Inverted velocity by FWI and volume-based MSWI with 9-20 Hz data

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Layer Salt Model

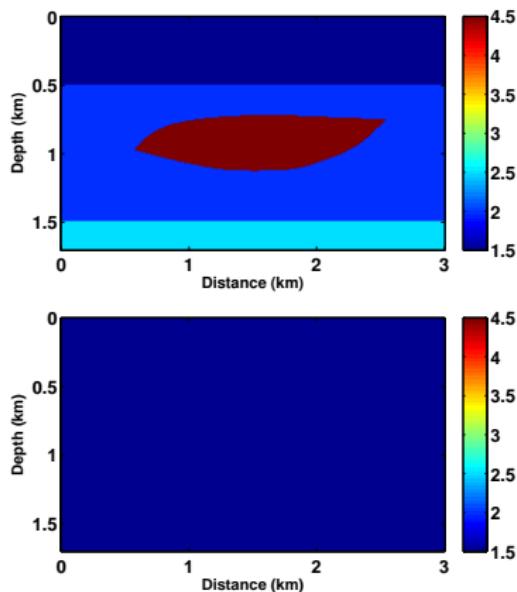


Figure: True model and constant initial model

Comparison of Results

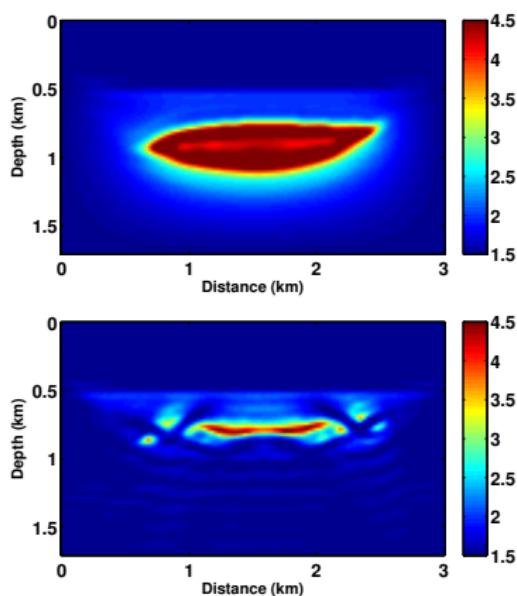


Figure: Inverted velocity by MSWI and FWI method with 6-12 Hz data

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Marmousi

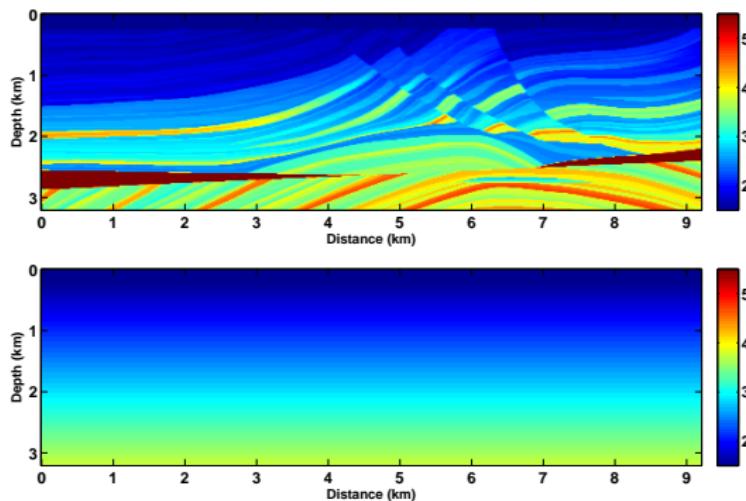


Figure: Marmousi model and 1D initial model

Marmousi

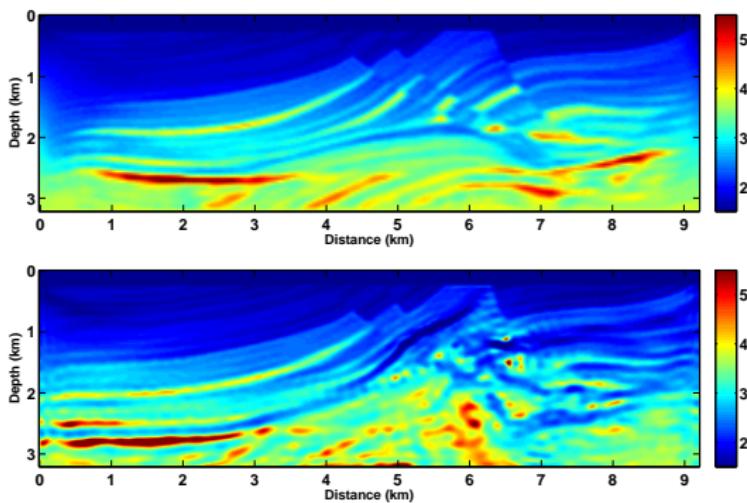


Figure: MSWI result (6-10 Hz data) and FWI result (4-8 Hz data)

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SEG/EAGE 2D Salt Model

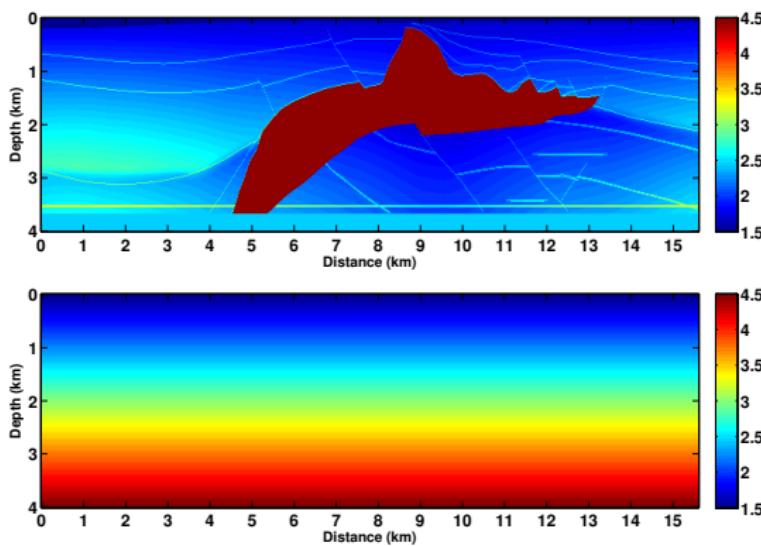


Figure: True model and 1D initial model

Inverted Results

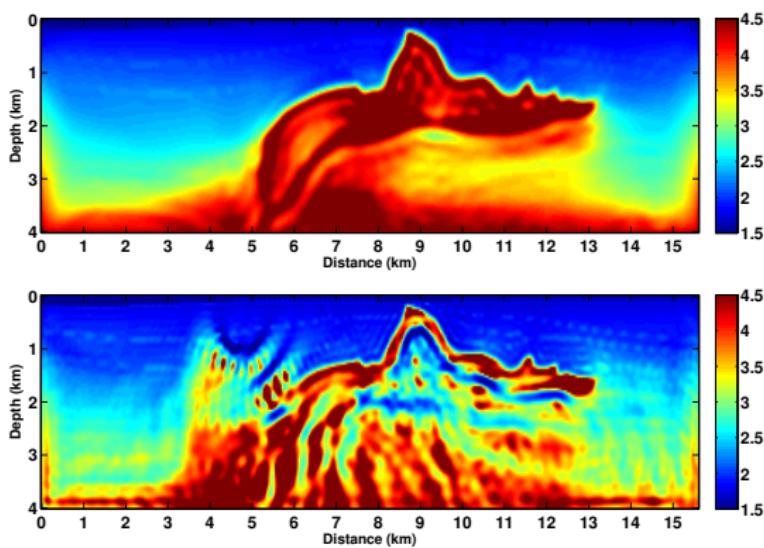


Figure: MSWI result and FWI result (3-6 Hz data)

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Slice of SEAM Phase I Model

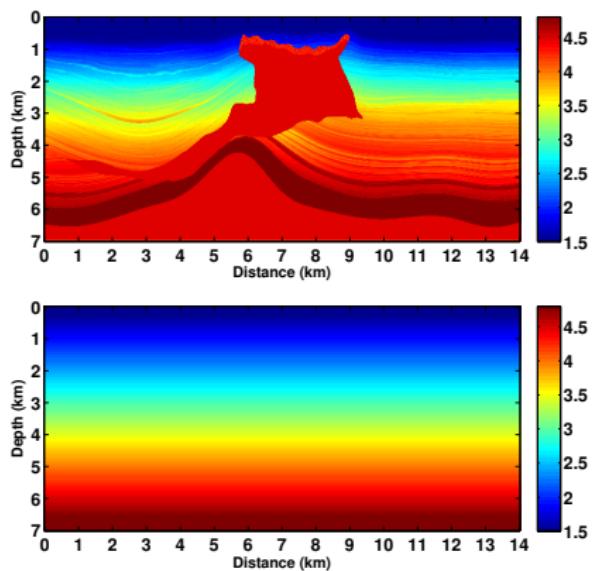


Figure: True model and 1D initial model

Inverted Result

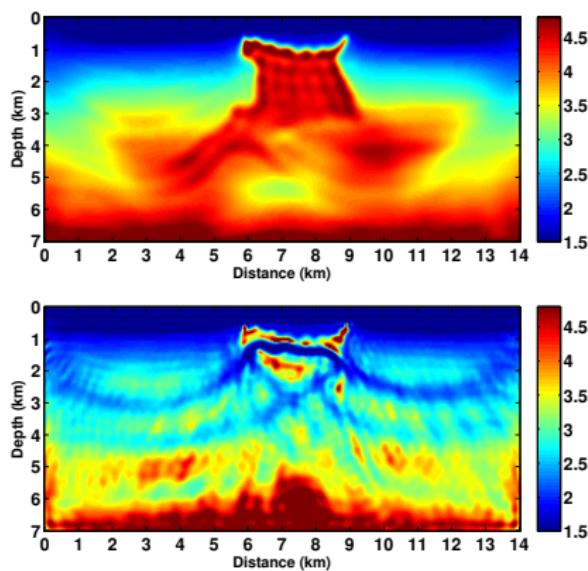


Figure: MSWI result (3-6 Hz data) and FWI result (2-5 Hz data)

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Slice of BP Model

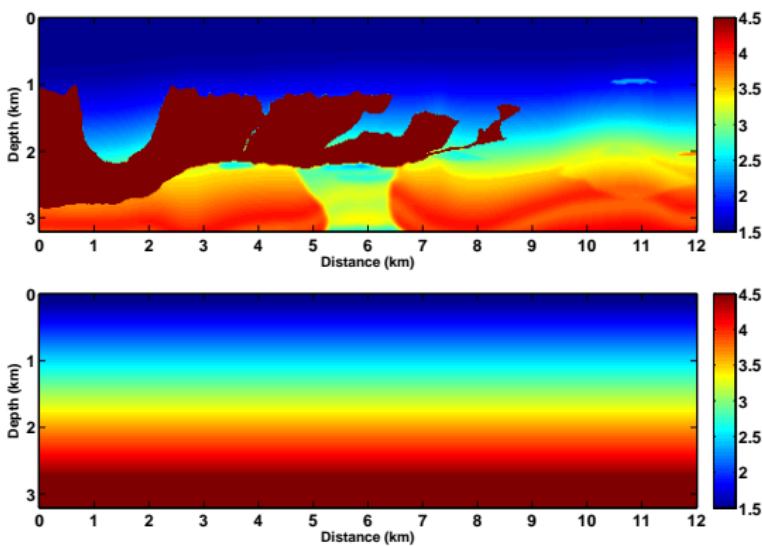


Figure: True model and 1D initial model

Inverted Results

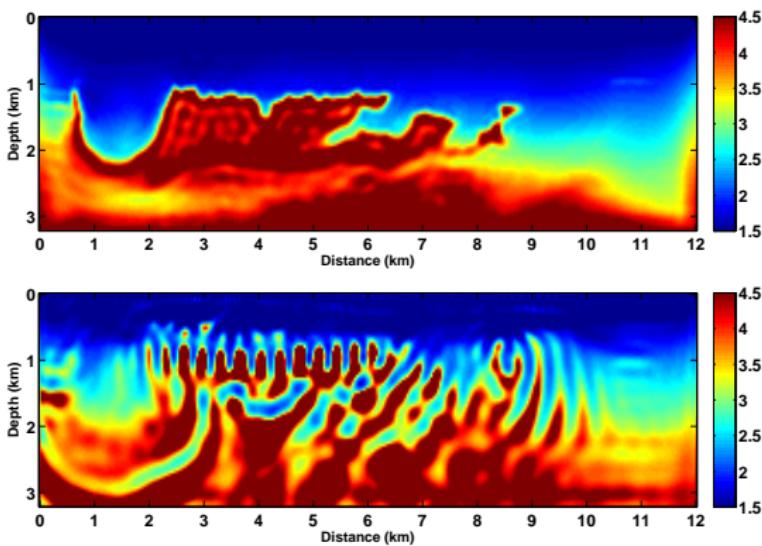


Figure: MSWI result (3-8 Hz data) and FWI result (2-5 Hz data)

Conclusion

- Nonlinear extended waveform inversion can handle reflection/refraction wave.
- No cycle skipping problem and insensitive to the frequency content and initial model.
- Equivalent to traveltime tomography under high frequency for transmission wave.
- Potential application in salt body reconstruction.
- How does it work for reflection wave?

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