

Gradients and Hessians for extended Born Waveform Inversion

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The Rice Inversion Project - Annual Review 2014



Waveform Inversion

- ▶ efficiency ?
- ▶ reliability ?
- ▶ value ?

Waveform Inversion

- ▶ efficiency ?
- ▶ reliability ?
- ▶ value ✓

Waveform Inversion

- ▶ FWI × (“cycle skipping”)
- ▶ extended FWI (“always fit data”)
 - ▶ Born-based (“IVA”)
 - ▶ Full-waveform based

Waveform Inversion

Theory \Rightarrow EFWI

Practice \Rightarrow FWI

What stands in the way of merging Theory with Practice: EFWI efficiency, **reliability**

Inversion Velocity Analysis

WEMVA, with ext'd LSM (Nemeth et al. 99,...)
= ext'd linearized inversion

IVA Objective function = focusing measure

Reliability issue: gradient accuracy (“artifacts” -
Fei & Williamson 10, Vyas & Tang 10, ...)

Inversion Velocity Analysis

Data $d \in$ Data Space D

Physical models $m \in$ physical model space M

Extended models (perturbational) $\delta \bar{m} \in$ ext'd model space \bar{M}

Inversion Velocity Analysis

Ext'd linearized fwd operator for
 $m \in M, : \bar{F}[m] : \bar{M} \rightarrow D$

Focus operator (“annihilator”) $A : \bar{M} \rightarrow \dots$

$$A\delta\bar{m} = 0 \Leftrightarrow \delta\bar{m} \in M \subset \bar{M}$$

Inversion Velocity Analysis

Can always fit data: $\bar{F}[m]$ “invertible”

$$J_{\text{IVA}}[m] = \frac{1}{2} \|A\bar{F}[m]^{-1}d\|^2$$

$\|u\|$ = RMS of u , $\langle u, v \rangle$ = dot product of u, v

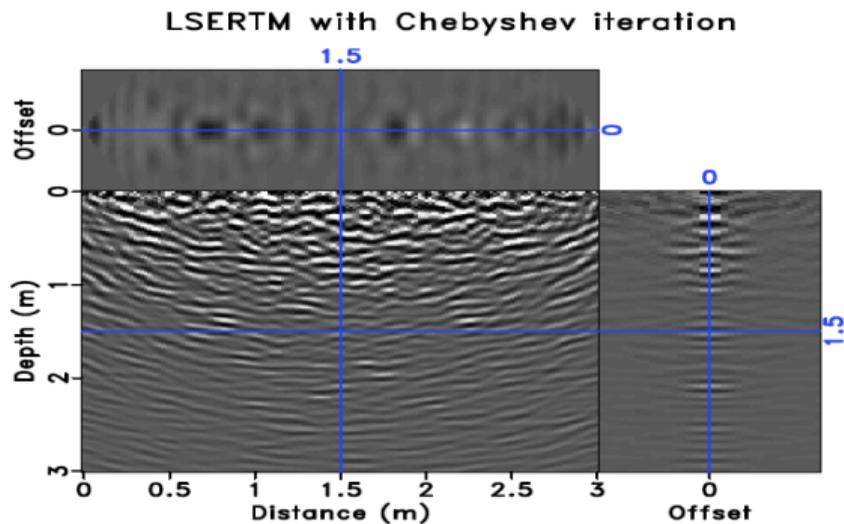
Inversion Velocity Analysis

Alternative: “traditional” WEMVA/DSO (Shen et al. 03,...):

$$J_{\text{MVA}}[m] = \frac{1}{2} \|A\bar{F}[m]^T d\|^2$$

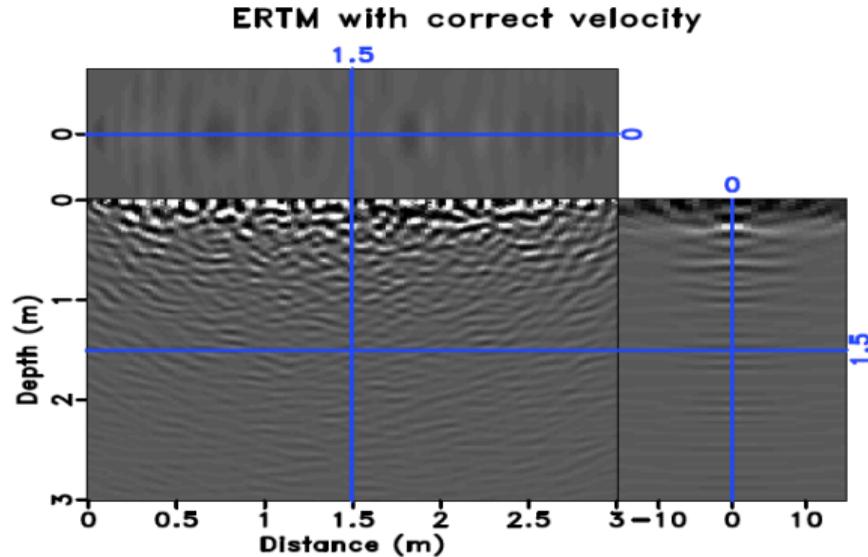
Example: 2D acoustics, subsurface offset extension (thanks: Y. Liu) ($A = \text{mult. by } h$)

Inversion Velocity Analysis



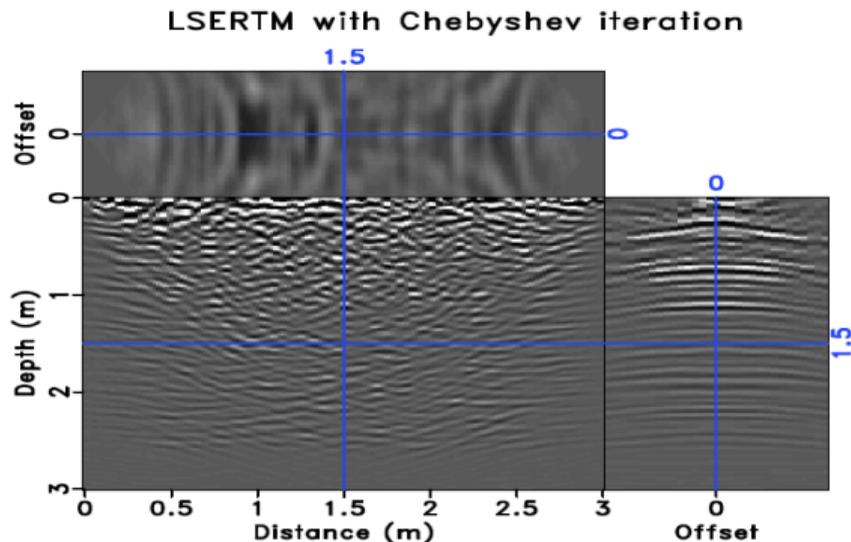
$$\delta \bar{m} \approx \bar{F}[m]^{-1} d: m = 1.00 * m_{\text{true}}$$

Inversion Velocity Analysis



$$\delta \bar{m} = \bar{F}[m]^T d: m = 1.00 * m_{\text{true}}$$

Inversion Velocity Analysis



$$\delta \bar{m} \approx \bar{F}[m]^{-1} d: m = 0.85 * m_{\text{true}}$$

Gradients

Gradient inaccuracy affects

- ▶ model resolution
- ▶ convergence rate of iterative optimization

Gradients

Computed gradient comparison, acoustics: Y. Liu, EAGE 14.

Densely sampled src, rec near surface, 10 Hz Ricker source

$m_{\text{true}} = 3 \text{ km/s}$. $\delta m_{\text{true}} = 3 \text{ trunc reflectors}$

Gradients

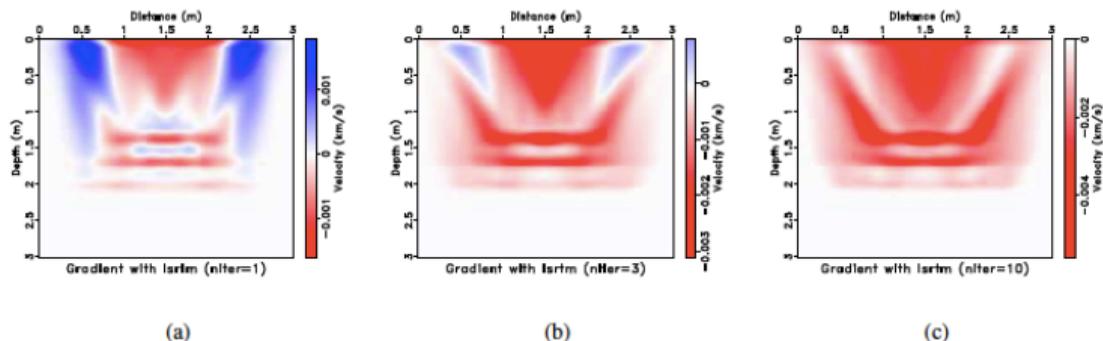


Figure 2 Background velocity gradient using extended reflectivity image by linearized inversion after different iteration number (a) iteration 1; (b) iteration 3; (c) iteration 10.

Left: ∇J_{MVA} - artifacts! Right: ∇J_{IVA} , at $m = 2.5$ km/s

Gradients

Rate of change: $m_+ = \delta m \Rightarrow$

$$\delta J_{\text{IVA}} = -\langle \bar{F}[m]^{-1} D\bar{F}[m](\delta m)\delta \bar{m}, A^T A\delta \bar{m} \rangle$$

$$\delta \bar{m} = \bar{F}[m]^{-1} d \Rightarrow 2 \text{ solves (iterative!)}$$

Gradients

Rate of change: $m_+ = \delta m \Rightarrow$

$$\delta J_{\text{MVA}} = \langle D\bar{F}[m]^T (\delta m)d, A^T A\bar{F}[m]^T d \rangle$$

\Rightarrow no iteration, ∇J_{MVA} is *exact* (except for FD error etc.) ! ???

Gradients

MVA: If “gradient artifacts” aren’t errors, what are they?

IVA: how does iterative approx. of F^{-1} affect computed gradient accuracy?

Analysis

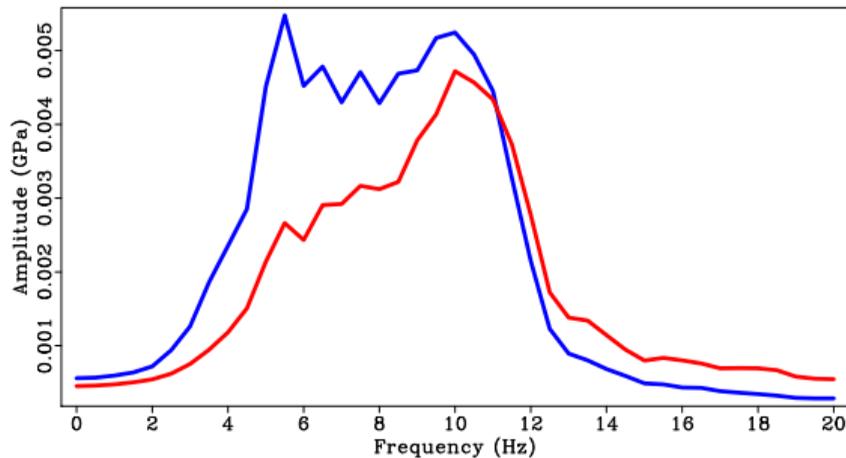
1st Key observation - “factorization lemma”:

$$D\bar{F}[m]\delta m = \bar{F}[m]Q[m, \delta m]$$

Q is (1) 1st order, (2) linear in δm ,
(3) skew-adjoint

(S. IPTA 14 & EAGE 15, ten Kroode IPTA 14)

Analysis



Avg spectra of \bar{F} (blue) and $D\bar{F}$ (red), Marmousi-derived Born modeling, 2.5-5-10-12.5 filter of delta half-deriv wavelet, norm. inc. plane wave

Analysis

MVA Hessian at consistent data:

$$d = \bar{F}[m]\delta\bar{m}_{\text{true}}, A\delta\bar{m}_{\text{true}} = 0$$

$$\delta^2 J_{\text{MVA}} = \langle \bar{F}^T \bar{F} \delta\bar{m}_{\text{true}}, Q^2 A^T A \bar{F}^T \bar{F} \delta\bar{m}_{\text{true}} \rangle + \dots$$

Lead term generically $\neq 0 \Rightarrow$ “true” model is not local min, gradient oscillates (Khoury 06)

Analysis

IVA Hessian at consistent data: many terms cancel,

$$\delta^2 J_{\text{IVA}} = \|[Q, A]\delta\bar{m}_{\text{true}}\|^2 + \text{l. o. t.}$$

Positive semi-definite 0-order form, proportional to tomographic Hessian

Analysis

$$\delta J_{\text{IVA}} = -\langle Q^T \delta \bar{m}, A^T A \delta \bar{m} \rangle$$

but

- ▶ can only approximate $\delta \bar{m}_{\text{approx}} \approx F[m]^{-1} d$
RMS - no control over derivs! ($Q!$)
- ▶ can only approximate $Q[m, \delta m] \delta \bar{m}$

Analysis

2nd Key observation: (Hou, ten Kroode,...)
computable *asymptotic* inverse \bar{F}^\dagger

$$\delta_{\text{approx}} J = \langle \bar{F}^\dagger D \bar{F} \delta \bar{m}_{\text{approx}}, A^T A \delta \bar{m}_{\text{approx}} \rangle$$

$\bar{F}^\dagger D \bar{F}$ also skew + 0-order $\Rightarrow \delta \bar{m}_{\text{approx}} \rightarrow \bar{F}^{-1} d$
 \simeq error in $\delta \bar{m}_{\text{approx}}$

$\bar{F}^\dagger D \bar{F} - Q$ is *smoothing* - $\bar{F}^\dagger D \bar{F} \rightarrow Q$
 $\simeq O(\text{wavelength})$.

Conclusion

- ▶ ∇J_{MVA} “artifacts” = feature, not bug
- ▶ J_{IVA} locally “as convex as refl. tomography” for noise-free data
- ▶ ELSM + asymptotic inverse op \Rightarrow error control for ∇J_{IVA}
- ▶ omitted: regularization, full waveform analog, elasticity

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- ▶ my very patient audience!