

Approximate Inverse Scattering Using Pseudodifferential Scaling

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- Present:
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Completed Masters Coursework in Physics
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Let:

- $m(x)$: The model (velocity, density, . . .)
- $p(x, t)$: The pressure field

Then, if S is the Forward Map:

- The Forward Problem:

$$S[m] = p|_{\text{surface}}$$

- The Inverse Problem:

$$S[m] \approx S^{obs}$$

Given S^{obs} , get $m(x)$

Nonlinear and Large Scale !

Linearization

If we have an approximation m_0 to the model, **Linearization** is advantageous:

- Write $m = m_0 + \delta m$
 m_0 : Given reference model
 δm : First order perturbation about m_0
- Define Linearized Forward Map $F[m_0]$ (Born Modeling):

$$F[m_0]\delta m = \delta p$$

- Reduce to the **Linear** Subproblem

$$F[m_0]\delta m \approx S^{obs} - S[m_0] := d$$



Normal Operator

Interpreted as a least squares problem, linear subproblem yields the normal equations

$$F^*[m_0]F[m_0]\delta m = F^*[m_0]d$$

$F^*[m_0]F[m_0]$ is the **Normal Operator**

The problem is still *Large Scale*, order of Pflops/Pbytes \Rightarrow cannot use direct methods to invert F^*F .

Properties of the normal operator have been extensively studied (Beylkin, 1985; Rakesh, 1988) for *smooth* m_0

- Nearly diagonal in the basis of localized monochromatic pulses (plane waves)
- Theoretical Setting: **Pseudodifferential** Operators



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The Eigenvalue Problem!

- Can compute $F^*[m_0]d$ and $F^*[m_0]F[m_0](\dots)$ (migration, e.g. RTM, Born Modeling+Migration)
- Know how to diagonalize $F^*[m_0]F[m_0]$
- *Don't* know the eigenvalues
- If we knew eigenvalues \Rightarrow Invert

How to compute the eigenvalues?

- Given $Ax = b$, with A S.P.D $\Rightarrow A = V^T \Lambda V$.
- Given b and Ab , applying A is very expensive!
- Given V , collection of eigenvectors.
- Given an algorithm that applies $V^T \Lambda V$ cheaply.
-

$$\Lambda_b = \underset{\Lambda}{\operatorname{argmin}} \|V^T \Lambda V b - Ab\|^2$$

- Now that we have Λ_b ,

$$A^{-1} = V^T \Lambda_b^{-1} V \Rightarrow x = A^{-1} b$$

- Spatial delta function approximation of eigenvectors \Rightarrow Diagonal Approximation of Hessian (Claerbout and Nichols, 1994; Rickett, 2003)
- Near Diagonal Approximation of Hessian (Guitton, 2004)
- Herrmann et al. (2007) use *curvelets* to approximate eigenvectors

An Alternative

An **alternative**, relying on the *asymptotic expansion lemma*:

Lemma

$$F^*[m_0]F[m_0]\chi(x)e^{i\omega\psi(x)} = q_m(x, \omega\nabla\psi(x))\chi(x)e^{i\omega\psi(x)} + O(\omega^{m-\beta})$$

ω is the frequency, $\beta > 0$, q_m **principal symbol** of order m .

$\chi(x)$ compactly supported in a small ball

- $\chi(x)e^{i\omega\psi(x)}$ localized monochromatic pulse: **eigenvectors**
- $q_m \approx \Lambda$ encodes the **eigenvalues**: Λ
 - $\chi(x)$ is localized
 - q_m is slowly varying



Approximation of Ψ DO

- The action of the Ψ DO (Bao and Symes, 1996):

$$Q_m u(x, z) \approx \int \int q_m(x, z, \xi, \eta) \hat{u}(\xi, \eta) e^{i(x\xi + z\eta)} d\xi d\eta$$

q_m is the principal symbol, homogeneous of degree m .
 $\hat{u} = \mathcal{F}[u]$.

- Direct Algorithm $O(N^4 \log(N))$ complexity!
- Writing $\xi = \omega \cos(\theta)$, $\eta = \omega \sin(\theta)$. Then,
 $q_m(x, z, \xi, \eta) = \omega^m \tilde{q}_m(x, z, \theta)$



$$\tilde{q}_m \approx \sum_{l=-K/2}^{l=K/2} c_l(x, z) e^{il\theta} = \sum_{l=-K/2}^{l=K/2} \omega^{-l} c_l(x, z) (\xi + i\eta)^l$$



$$Q_m u \approx \sum_{l=-K/2}^{l=K/2} c_l(x, z) \mathcal{F}^{-1}[\omega^{m-l}(\xi + i\eta)^l \hat{u}(\xi, \eta)]$$

- 1 Calculate $\hat{u} = \mathcal{F}[u]$
- 2 Calculate $\mathcal{F}^{-1}[\omega^{m-l}(\xi + i\eta)^l \hat{u}(\xi, \eta)]$
- 3 Calculate $c_l(x, z) \approx \mathcal{F}[\tilde{q}_m]$
- 4 Estimate $Q_m u$

Use FFT $\Rightarrow O(KN^2[\log(N) + \log(K)])$ complexity vs $O(N^4 \log(N))$ complexity for the direct algorithm. K independent of N .

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Inversion

Given the migrated image $m_{mig} = F^*d$, and the remigrated image $m_{remig} = F^*Fm_{mig}$

$$q_m = \underset{\tilde{q}_m \geq 0}{\operatorname{argmin}} \|Q_m[\tilde{q}_m]m_{mig} - m_{remig}\|^2$$

Let

$$q^\dagger = \frac{1}{q_m + \varepsilon}, \quad \varepsilon > 0$$

be the pseudoinverse of q_m and obtain an approximate inverse

$$\delta m \approx Q_m[q^\dagger]m_{mig}$$

We obtain a **Scaling Method**.



- Implement Bao and Symes (1996) Algorithm:
Discretizations, FFT...

The Master Plan

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- Use Finite Difference Born and Adjoint Modeling (RTM) to
compute: m_{mig} , m_{remig} , ...

The Master Plan

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Discretizations, FFT...
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- Get a Masters !

- When m_0 is a good approximation:
 - Fast solution of the Linear Inverse Problem
 - Variable density acoustics
 - Linear Elasticity
- When m_0 is not a good approximation:
 - View the linear problem as a Newton step
 - **Preconditioning** of iterative methods

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- Normal Operator is
 - Pseudodifferential
 - Nearly diagonal in basis of localized monochromatic pulses
- Efficient Algorithm to apply a Ψ DO
- **Scaling Method**
 - Fast and reliable solution if m_0 is a good approximation
 - Preconditioning iterative methods if m_0 is not a good approximation

THANK YOU !

